



Football Game Based Optimization: an Application to Solve Energy Commitment Problem

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Abstract: Heuristic optimization algorithms are widely used to solve problems in different fields of science. In this paper, a new game based optimization method called football game based optimization (FGBO) is presented which simulates the game of football. The population of FGBO are clubs and the variables of the problem are the players belonging to the clubs. FGBO has four phases: a) league holding, b) player transfer, c) practice, and d) promotion and relegation. The power of FGBO in solving optimization problems has been investigated on several benchmark test functions. The result of FGBO and other algorithm are obtained from implantation of these algorithms on unimodal, multimodal, and fixed-dimension multimodal benchmark test functions. Eight optimization algorithms called Genetic Algorithm (GA), Particle Swarm Optimization (PSO), Teaching Learning Based Optimization (TLBO), Grey Wolf Optimizer (GWO), Grasshopper Optimization Algorithm (GOA), Emperor Penguin Optimizer (EPO), Shell Game Optimization (SGO), and Hide Objects Game Optimization (HOGO) have been used to compare these results. The proposed FGBO algorithm is also used to solve the energy commitment (EC) problem. Based on the simulation studies and obtained results, FGBO has a higher efficiency than a number of other algorithms. The results and data obtained from applying FGBO and other mentioned algorithms on unimodal test functions, multimodal test functions, and energy commitment problem show that FGBO is able to provide better results in comparison with other well-known optimization algorithms.

Keywords: Energy commitment, Football, Football game based optimization, Game, Game based algorithms, Optimization.

1. Introduction

1.1 Motivation

In recent decades, heuristic optimization algorithms have been widely used in applied science field. The power of these algorithms to solve optimization problems is undeniable. Such algorithms have demonstrated their high ability in many fields such as energy [1], protection [2], electrical engineering [3-7], and energy carriers [8, 9] to achieve the optimal solution.

1.2 Contribution

In recent years, the use of optimization algorithms has become very common. Numerous algorithms have been proposed by scientists, most of which are based on the laws of physics, evolution, and swarm activities. However, mathematical modeling of phenomena in which the process of evolution and progress lies, can provide new optimizers. Game is a social activity in which participants, called game players, try to win according to the rules of the game. Therefore, simulating this process of achieving

victory considering the rules of the game, can lead to the design of new optimization algorithms.

A new game based optimization method, called football game based optimization (FGBO) that simulates the game of football, is proposed in this paper. The population of FGBO is clubs and the variables of the problem are the players in the clubs. FGBO has three phases: a) league holding, b) player transfer, c) practice, and d) promotion and relegation.

Many of the scientists' proposed optimization algorithms face two challenges: complexity of the equations and setting multiple control parameters. However, the simplicity of the equations and the lack of control parameters, as well as the implementation of the proposed algorithm of the authors of this paper, are important features of FGBO. Therefore, FGBO can be easily applied to any optimization problem. The performance of FGBO has been compared to eight well-known optimization techniques considering twenty-three linear and nonlinear benchmark test functions. Moreover, FGBO has been tested on an engineering optimization problem named energy commitment to validate its effectiveness.

1.3 Paper organization

A background of the optimization algorithms is given in Section 2. The proposed football game based optimization algorithm is presented in Section 3. Simulation results are described in Section 4 and conclusions are drawn in Section 5.

2. Background

Each optimization problem is mathematically modeled in three parts, including objective functions, variables, and constraints. The goal in optimization is to minimize or maximize the objective functions considering constraints. There are several ways to solve an optimization problem. One of these methods is optimization algorithms, which always have a high ability to solve optimization problems. Optimization algorithms, without the need for a derivation process, provide a quasi-optimal answer by randomly searching in the defined space of the variables. The term quasi-optimization is used because optimization algorithms randomly check the search space may not be able to achieve the optimal answer. However, the quasi-optimal answer is an answer close to the optimal answer. Therefore, the advantage of one algorithm over another algorithm is in providing a quasi-optimal answer that is very close to the optimal answer. Due to this, several optimization algorithms have been developed by researchers to obtain more appropriate answers. In the theoretical mode, the

difference between optimization algorithms is in main design idea, the complexity of the equations, and the existence of control parameters and their adjustment. However, in order to compare optimization algorithms more deeply, these algorithms should be implemented on optimization problems and analyzed based on the obtained results.

Heuristic optimization algorithms can be divided into four categories. These categories are: physics-based algorithm, swarm-based algorithm, game-based algorithm, and evolution-based algorithms.

2.1 Physics-based algorithm

Physics-based algorithms are based on the simulation of the rules of physics. Some of this kind of algorithms are: Black Hole (BH) [10] based on black hole phenomenon, Gravitation Search Algorithm (GSA) [11] based on gravitational gravity force, Spring Search Algorithm (SSA) [12, 13] inspired by Hooke's law, Charged System Search (CSS) [14] based on some principles from physics and mechanics where each agent is a charged particle, Curved Space Optimization (CSO) [15] based on transformation of a random search space into a new search space based on the concepts of space-time curvature in general relativity theory, Galaxy-based Search Algorithm (GbSA) [16] based on spiral arm of spiral galaxies, Ray Optimization (RO) [17] algorithm based on the Snell's light refraction law, Small World Optimization Algorithm (SWOA) [18] based on mechanism of small-world phenomenon, and Artificial Chemical Reaction Optimization Algorithm (ACROA) [19] based on chemical reactions processes.

2.2 Swarm-based algorithm

Swarm-based algorithms are inspired from the natural processes of plants, foraging behavior of insects and social behavior of animals. Some of the known optimization algorithms belonging to this category are: Donkey Theorem Optimization (DTO) [20], Particle Swarm Optimization (PSO) [21], Artificial Bee Colony (ABC) [22], Ant Colony Optimization (ACO) [23], Bat-inspired Algorithm (BA) [24], Emperor Penguin Optimizer (EPO) [25], Spotted Hyena Optimizer (SHO) [26], Gray Wolf Optimizer (GWO) [27], Cuckoo Search (CS) [28], Following Optimization Algorithm (FOA) [29], Rat Swarm Optimizer (RSO) [30], Group Optimization (GO) [31], and Grasshopper Optimization Algorithm (GOA) [32].

2.3 Game-based algorithm

Some optimization algorithms such as Orientation Search Algorithm (OSA) [33] which simulates rules of orientation game or Dice Game Optimizer (DGO) [34] that simulates the rules of an old game named dice game are the members of Game-based algorithms which are based on simulation of different games. Shell Game Optimization (SGO) [35], Hide Objects Game Optimization (HOGO) [36], and Darts Game Optimizer (DGO) [37] are part of this group of algorithms.

2.4 Evolution-based algorithms

Evolutionary algorithms have involved evolution of a population in order to create new generations of genetically superior individuals [38]. Differential Evolution (DE) [39], Genetic Algorithm (GA) [40], Genetic Programming (GP) [41], Evolution Strategy (ES) [42], and Biogeography-based Optimizer (BBO) [43] are part of this group of algorithms.

3. Football game based optimization (FGBO)

In this paper, an optimization method named Football game based optimization, which simulates the football game, is presented. FGBO is simulated in four phases: a) league holding, b) player transfer, c) practice, and d) promotion and relegation.

Population of FGBO are clubs that are specified by Eq. (1):

$$C_i = [c_i^1, \dots, c_i^d, \dots, c_i^m] \quad (1)$$

Here, C_i is i -th club, c_i^d is d -th member of i -th club, and m is the number of players.

The power of clubs is evaluated by Eq. (2) and the best club is specified by Eq. (3):

$$P_i = \frac{fit_i - \max(fit)}{\sum_{j=1}^N [fit_j - \max(fit)]} \quad (2)$$

$$C_{best} = \text{the position of } \min(fit) \quad (3)$$

Here, P_i is the power of the i -th club, fit_i is the fitness function of i -th agent, and N is the number of clubs.

3.1 League holding

There are three modes for each club in each game. In fact, the outcome of a match for a club may be a

win, a loss or a draw that are simulated by Eqs. (4) to (8).

$$z_i^{win} = 0.95 \frac{P_i}{P_i + P_j} \quad (4)$$

$$z_i^{loss} = 0.95 \frac{P_j}{P_i + P_j} \quad (5)$$

$$z_i^{draw} = 1 - (z_i^{win} + z_i^{loss}) = 0.05 \quad (6)$$

$$S_{i,j} = \begin{cases} 3, & 0 < r < z_i^{win} \\ 1, & z_i^{win} < r < 1 - z_i^{loss} \\ 0, & \text{else} \end{cases} \quad (7)$$

$$S_{j,i} = \begin{cases} 0, & 0 < r < z_i^{win} \\ 1, & z_i^{win} < r < 1 - z_i^{loss} \\ 3, & \text{else} \end{cases} \quad (8)$$

Here, z_i^{win} , z_i^{loss} , and z_i^{draw} are the probability of winning, losing, and drawing of the i -th club, and $S_{i,j}$ is the score of the i -th club in face of j -th club.

3.2 Player transfer

In this phase, each club employs a few new players based on their points. This phase is simulated by Eq. (9) to by Eq. (11).

$$N_{pt_i} = \text{round} \left[0.5 \times m \left(1 - \frac{t}{T} \right) \times \left(\frac{rank_i - 1}{N - 1} \right) \right] \quad (9)$$

$$D_{pt_i} = \text{randperm}(m, N_{pt_i}) \quad (10)$$

$$C_i(D_{pt_i}) = C_{best}(D_{pt_i}) \quad (11)$$

Here, N_{pt_i} is the number of transitional players to i -th club, t is the number of iteration, T is the maximum number of iterations, $rank_i$ is the position of i -th club in league table, and D_{pt_i} is the position of transferred players to i -th club.

3.3 Practice

In this phase, each club is trying to improve its situation with practice. In fact, a new agent (club) is created in the neighborhood of each agent (club). If the new agent is better, the status of the club will be updated. This phase is simulated by Eq. (12) to Eq. (14).

$$C'_i = (1 - I_{P_i})C_i + I_P C_{best} \quad (12)$$

$$I_{P_i} = 0.2 \frac{rank_i}{N} \left(1 - \frac{t}{T} \right) \quad (13)$$

$$C_i = \begin{cases} C_i, & \text{fit}_i < \text{fit}'_i \\ C'_i, & \text{else} \end{cases} \quad (14)$$

Here, C'_i is the status and fit'_i is the fitness function of i -th club after practice. In addition, I_{P_i} is the index of prace.

3.4 Promotion and Relegation

In this phase, some poor clubs are eliminated from the league and some new qualified clubs substitute them in the league. This process is simulated by (15) to (16).

$$N_{pr} = 0.1 \times N \times \left(1 - \frac{t}{T}\right) \quad (15)$$

$$C_i = C_i + 2 \times \text{rand} \times (C_{best} - C_i) \\ \& i = N - N_{pr} + 1 : N \quad (16)$$

Here, N_{pr} is the number of promoted or relegated clubs.

The various steps of FGBO are as follows:

Start

- a) Set up the system.
- b) The initial status of the clubs.
- c) Evaluation of clubs.
- d) C_{best} and power update.
- e) Phase a: league holding (4) to (8).
- f) Phase b: player transfer (9) to (11).
- g) Phase c: practice (12) to (14).
- h) Phase d: promotion and relegation (15) to (16).
- i) Update of the status of the clubs.
- j) As long as the stop condition is not satisfied, repeat steps c to i.

End

4. Simulation

In this section the performance of the FGBO is evaluated by applying the standard benchmark test functions adapted from [44]. In order to demonstrate the effectiveness of the FGBO, it is compared with eight well-known optimization algorithms (GA, PSO, TLBO, GWO, GOA, EPO, SGO, and HOGO) on unimodal, multimodal, and fixed-dimension multimodal benchmark test functions.

The experimentation has been done on MATLAB R2014a version in the environment of Microsoft Windows 7 using 64 bit Core i-7 processor with 2.40 GHz and 8 GB main memory. The average and standard deviations of the best optimal solution are mentioned in Tables 1-3.

4.1 Unimodal test functions with high dimension

The results of evaluation of FGBO and other algorithms on functions F_1 to F_7 given in Table 1 show that FGBO has better performance than other algorithms in all Unimodal test functions with high dimension. In Table 1, Avg and std stand for average value and standard deviation of obtained results.

4.2 Multimodal test functions with high dimension

In multimodal test functions, F_8 to F_{13} , the number of local solutions increases exponentially with increasing function dimensions. Therefore, it is hardly possible to achieve the global minimum in these types of functions. Instead, reaching the nearest solution to global minimum indicates the high power of the algorithm in passing the wrong local solution. The results of evaluating functions F_8 to F_{13} are shown in Table 2. In all of these functions, FGBO shows better performance.

4.3 Multimodal test functions with low dimension

Functions F_{14} to F_{23} have a low number of dimensions and they also have few local minimums. Results of the 20-time implementation of FGBO and other algorithms are presented in Table 3. These results show the proper performance of FGBO in optimizing these types of functions.

4.4 theoretical explanation and discussion

Two important indicators in comparing the ability of optimization algorithms in solving optimization problems are exploration and exploitation power. The exploration index examines the ability of an optimization algorithm to search properly and comprehensively in the search space of the problem. Therefore, an optimization algorithm that searches the search space more accurately has higher exploration power. This prevents the algorithm from getting stuck in local optimizations points. The exploitation index is the study of the ability of an optimization algorithm to provide an appropriate quasi-optimal response. Therefore, an algorithm that provides a quasi-optimal answer closer to the optimal answer has a higher exploitation power. The important principle is to maintain a balance between these two indicators during the repetition of the algorithm. Thus, in the initial iterations, the exploration power should be a priority so that the search space is searched accurately. Then, with the repetition of the algorithm repetitions, the exploration power is reduced and the exploitation power is given priority so that the quasi-optimal answer is presented.

Based on this important principle, an algorithm that can accurately search the problem search space is able to provide a better quasi-optimal answer. The proposed FGBO algorithm, by maintaining a proper balance between the two exploration and exploitation indicators, has been able to provide appropriate quasi-optimal answers for all three types of unimodal, multimodal, and fixed-dimension multimodal objective functions.

The results presented in Tables 1 to 3 show that the proposed FGBO algorithm has a clear advantage over all other eight algorithms in all twenty-three objective functions. Functions F₁ to F₇ have been proposed to analyze the exploitation ability of optimization algorithms. According to Table 1, FGBO has higher exploitation ability than the other eight algorithms.

Objective functions F₈ to F₂₃ have also been proposed to analyze the exploration capability of optimization algorithms. Based on Tables 2 and 3, the proposed FGBO algorithm has a higher exploration capability than the other eight algorithms.

5. FGBO for energy commitment solving

In this section, FGBO performance is assessed on the energy commitment (EC) problem. Energy consumption is an important indicator in determining the quality of life in any society. Therefore, the proper use of energy resources and carriers is an important principle in energy operation. The goal of EC is to determine the most appropriate way to use energy carriers to meet energy demand by taking into account technical and economic constraints. Therefore, EC is a constrained optimization problem that can be solved using optimization algorithms [9].

Unit commitment (UC) is one of the important studies of electricity networks. The purpose of UC is to determine the most appropriate composition and production of power plant for each hour of the study period to supply demand considering technical and economic constraints. In UC, the operation of the power carrier is optimized independently. However, the interdependencies between different energy networks make integrated energy network studies very important. The demand of energy consumers at different levels consists of different types of energy carriers such as gas, electricity, gasoline, etc., which must be optimally supplied. The study of EC optimizes this operation. In EC, the objective function is to reduce the operating costs of different energy carriers in order to meet energy demand, decision-making variables are the amount of energy carriers, and the most important constraint is the balance of energy supply and demand.

Table 1. Results for FGBO and other algorithms in Unimodal test functions

	GA		PSO		TLBO		GWO		GOA		EPO		SGO		HOGO		FGBO		
	Ave.	std	Ave.	std	Ave.	std	Ave.	std	Ave.	std	Ave.	std	Ave.	std	Ave.	std	Ave.	std	
F ₁	1.95×10 ⁻¹²	2.01×10 ⁻¹¹	4.98×10 ⁻⁹	1.40×10 ⁻⁸	3.55×10 ⁻²	1.06×10 ⁻¹	7.86×10 ⁻¹⁰	8.11×10 ⁻⁹	2.81×10 ⁻¹	1.11×10 ⁻¹	5.71×10 ⁻²⁸	8.31×10 ⁻²⁹	6.74×10 ⁻³⁵	9.17×10 ⁻³⁶	4.36×10 ⁻³⁶	6.84×10 ⁻³⁷	2.64×10 ⁻³⁸	8.56×10 ⁻⁴⁰	
F ₂	6.53×10 ⁻¹⁸	5.10×10 ⁻¹⁷	7.29×10 ⁻⁴	1.84×10 ⁻³	3.23×10 ⁻⁵	8.57×10 ⁻⁵	5.99×10 ⁻²⁰	1.11×10 ⁻¹⁷	3.96×10 ⁻¹	6.20×10 ⁻⁴⁰	3.32×10 ⁻⁴⁰	7.78×10 ⁻⁴⁵	3.48×10 ⁻⁴⁵	7.78×10 ⁻⁴⁵	5.89×10 ⁻⁴⁹	6.84×10 ⁻⁵¹	7.95×10 ⁻⁴⁶	6.84×10 ⁻⁵¹	
F ₃	7.70×10 ⁻¹⁰	7.36×10 ⁻⁹	1.40×10 ⁺¹	7.13	4.91×10 ⁺³	3.89×10 ⁺³	9.19×10 ⁻⁵	6.16×10 ⁻⁴	4.31×10 ⁺¹	2.05×10 ⁻¹⁹	2.05×10 ⁻¹⁹	2.63×10 ⁻²⁵	2.63×10 ⁻²⁵	2.63×10 ⁻²⁵	6.85×10 ⁻²⁶	6.85×10 ⁻²⁶	5.61×10 ⁻²⁷	5.61×10 ⁻²⁷	
F ₄	9.17×10 ⁺¹	5.67×10 ⁺¹	6.00×10 ⁻¹	1.72×10 ⁻¹	1.87×10 ⁺¹	8.21	8.73×10 ⁻¹	1.19×10 ⁻¹	8.80×10 ⁻¹	2.50×10 ⁻¹	4.32×10 ⁻¹⁸	9.17×10 ⁻²⁰	4.65×10 ⁻²⁶	4.65×10 ⁻²⁶	2.15×10 ⁻²⁷	2.15×10 ⁻²⁷	2.54×10 ⁻²⁹	2.54×10 ⁻²⁹	
F ₅	5.57×10 ⁻²	4.16×10 ⁻¹	4.93×10 ⁺¹	3.89×10 ⁺¹	7.37×10 ⁺²	1.98×10 ⁺³	8.91×10 ⁺²	2.97×10 ⁺²	1.18×10 ⁺²	1.43×10 ⁺²	5.07	4.90×10 ⁻¹	5.41×10 ⁻¹	5.41×10 ⁻¹	3.84×10 ⁻²	3.84×10 ⁻²	1.24×10 ⁻¹	2.51×10 ⁻⁴	
F ₆	3.15×10 ⁻¹	9.98×10 ⁻²	9.23×10 ⁻⁹	1.78×10 ⁻⁸	4.88	9.75×10 ⁻¹	8.18×10 ⁻¹⁷	1.70×10 ⁻¹⁸	3.15×10 ⁻¹	7.01×10 ⁻¹⁹	4.39×10 ⁻²⁰	8.03×10 ⁻²⁴	8.03×10 ⁻²⁴	8.03×10 ⁻²⁴	2.69×10 ⁻²⁶	2.69×10 ⁻²⁶	5.74×10 ⁻³⁰	5.74×10 ⁻³⁰	
F ₇	6.79×10 ⁻⁴	3.29×10 ⁻³	6.92×10 ⁻²	2.87×10 ⁻²	3.88×10 ⁻²	5.79×10 ⁻²	5.37×10 ⁻¹	1.89×10 ⁻¹	2.02×10 ⁻²	2.71×10 ⁻⁵	9.26×10 ⁻⁶	3.33×10 ⁻⁸	3.33×10 ⁻⁸	3.33×10 ⁻⁸	1.85×10 ⁻⁹	1.85×10 ⁻⁹	6.54×10 ⁻¹¹	6.54×10 ⁻¹¹	

Table 3. Results for FGBO and other algorithms in multimodal test functions with low dimension

	GA	PSO	TLBO	GWO	GOA	EPO	SGO	HOGO	FGBO
F ₁₄	Ave	4.39	2.77	6.79	1.26	9.98×10 ⁺¹	1.08	9.98×10 ⁻¹	5.62×10 ⁻⁵
	std	4.41×10 ⁻²	2.32	1.12	6.86×10 ⁻¹	9.14×10 ⁻¹	4.11×10 ⁻²	7.64×10 ⁻¹²	5.25×10 ⁻¹²
F ₁₅	Ave	7.36×10 ⁻²	9.09×10 ⁻³	5.15×10 ⁻²	1.01×10 ⁻²	7.15×10 ⁻²	8.21×10 ⁻³	3.3×10 ⁻⁴	2.01×10 ⁻⁵
	std	2.39×10 ⁻³	2.38×10 ⁻³	3.45×10 ⁻³	3.75×10 ⁻³	1.26×10 ⁻¹	4.09×10 ⁻³	1.25×10 ⁻⁵	5.26×10 ⁻⁶
F ₁₆	Ave	-1.02	-1.02	-1.01	-1.02	-1.02	-1.02	-1.03	-1.03
	std	4.19×10 ⁻⁷	0.00	3.64×10 ⁻⁸	3.23×10 ⁻⁵	4.74×10 ⁻⁸	9.80×10 ⁻⁷	5.12×10 ⁻¹⁰	3.26×10 ⁻¹⁰
F ₁₇	Ave	3.98×10 ⁻¹	3.98×10 ⁻¹	3.98×10 ⁻¹	3.98×10 ⁻¹	3.98×10 ⁻¹	3.98×10 ⁻¹	3.98×10 ⁻¹	3.98×10 ⁻¹
	std	3.71×10 ⁻¹⁷	9.03×10 ⁻¹⁶	9.45×10 ⁻¹⁵	7.61×10 ⁻⁴	1.15×10 ⁻⁷	5.39×10 ⁻⁵	4.56×10 ⁻²¹	2.45×10 ⁻²¹
F ₁₈	Ave	3.00	3.00	3.00	3.00	3.00	3.00	3.00	3.00
	std	6.33×10 ⁻⁷	6.59×10 ⁻⁵	1.94×10 ⁻¹⁰	2.25×10 ⁻⁵	1.48×10 ⁺¹	1.15×10 ⁻⁸	1.15×10 ⁻¹⁸	4.61×10 ⁻¹⁹
F ₁₉	Ave	-3.81	-3.80	-3.73	-3.75	-3.77	-3.86	-3.86	-3.86
	std	4.37×10 ⁻¹⁰	3.37×10 ⁻¹⁵	9.69×10 ⁻⁴	2.55×10 ⁻³	3.53×10 ⁻⁷	6.50×10 ⁻⁷	5.61×10 ⁻¹⁰	6.23×10 ⁻¹¹
F ₂₀	Ave	-2.39	-3.32	-2.17	-2.84	-3.23	-2.81	-3.31	-3.31
	std	4.37×10 ⁻¹	2.66×10 ⁻¹	1.64×10 ⁻¹	3.71×10 ⁻¹	5.37×10 ⁻²	7.11×10 ⁻¹	4.29×10 ⁻⁵	2.95×10 ⁻⁵
F ₂₁	Ave	-5.19	-7.54	-7.33	-2.28	-7.38	-8.07	-10.15	-10.15
	std	2.34	2.77	1.29	1.80	2.91	2.29	1.25×10 ⁻²	1.05×10 ⁻³
F ₂₂	Ave	-2.97	-8.55	-1.00	-3.99	-8.50	-10.01	-10.40	-10.40
	std	1.37×10 ⁻²	3.08	2.89×10 ⁻⁴	1.99	3.02	3.97×10 ⁻²	3.65×10 ⁻⁷	3.25×10 ⁻⁸
F ₂₃	Ave	-3.10	-9.19	-2.46	-4.49	-8.41	-3.41	-10.53	-10.55
	std	2.37	2.52	1.19	1.96	3.13	1.11×10 ⁻²	5.26×10 ⁻⁶	2.91×10 ⁻⁶

Table 2. Results for FGBO and other algorithms in multimodal test functions

	GA	PSO	TLBO	GWO	GOA	EPO	SGO	HOGO	FGBO
F ₈	Ave	-5.11×10 ⁺²	-5.01×10 ⁺²	-3.81×10 ⁺²	-4.69×10 ⁺¹	-6.92×10 ⁺²	-8.76×10 ⁺²	-1.2×10 ⁺⁴	-1.2×10 ⁺⁴
	std	4.37×10 ⁺¹	4.28×10 ⁺¹	2.83×10 ⁺¹	3.94×10 ⁺¹	9.19×10×10 ⁺¹	5.92×10 ⁺¹	9.14×10 ⁻¹²	8.72×10 ⁻¹²
F ₉	Ave	1.23×10 ⁻¹	1.20×10 ⁻¹	2.23×10 ⁻¹	4.85×10 ⁻²	1.01×10 ⁺²	6.90×10 ⁻¹	8.76×10 ⁻⁴	5.62×10 ⁻⁴
	std	4.11×10 ⁺¹	4.01×10 ⁺¹	3.25×10 ⁺¹	3.91×10 ⁺¹	1.89×10 ⁺¹	4.81×10 ⁻¹	4.85×10 ⁻²	3.21×10 ⁻²
F ₁₀	Ave	5.31×10 ⁻¹¹	5.20×10 ⁻¹¹	1.55×10 ⁻¹	2.83×10 ⁻⁸	1.15	8.03×10 ⁻¹⁶	8.04×10 ⁻²⁰	2.61×10 ⁻²⁰
	std	1.11×10 ⁻¹⁰	1.08×10 ⁻¹⁰	8.11	4.34×10 ⁻⁷	7.87×10 ⁻¹	2.74×10 ⁻¹⁴	3.34×10 ⁻¹⁸	2.14×10 ⁻¹⁸
F ₁₁	Ave	3.31×10 ⁻⁶	3.24×10 ⁻⁶	3.01×10 ⁻¹	2.49×10 ⁻⁵	5.74×10 ⁻¹	4.20×10 ⁻⁵	4.23×10 ⁻¹⁰	1.56×10 ⁻¹⁰
	std	4.23×10 ⁻⁵	4.11×10 ⁻⁵	2.89×10 ⁻¹	1.34×10 ⁻⁴	1.12×10 ⁻¹	4.73×10 ⁻⁴	5.11×10 ⁻⁷	4.15×10 ⁻⁷
F ₁₂	Ave	9.16×10 ⁻⁸	8.93×10 ⁻⁸	5.21×10 ⁻¹	1.34×10 ⁻⁵	1.27	5.09×10 ⁻³	6.33×10 ⁻⁵	4.87×10 ⁻⁵
	std	4.88×10 ⁻⁷	4.77×10 ⁻⁷	2.47×10 ⁻²	6.23×10 ⁻⁴	1.02	3.75×10 ⁻³	4.71×10 ⁻⁴	3.96×10 ⁻⁴
F ₁₃	Ave	6.39×10 ⁻²	6.26×10 ⁻²	2.81×10 ⁻²	9.94×10 ⁻⁸	6.60×10 ⁻²	1.25×10 ⁻⁸	0.00	0.00
	std	4.49×10 ⁻²	4.39×10 ⁻²	8.63×10 ⁻²	2.61×10 ⁻⁷	4.33×10 ⁻²	2.61×10 ⁻⁷	0.00	0.00

The mathematical model of energy commitment, including the objective function and constraint, is as follows:

$$F_{objective} = \min \left\{ \sum_{t=1}^T \left[\sum_{i=1}^{N_c} carrier_i^t \times price_i + \sum_{i=1}^{N_g} SC_i^t + \sum_{i=1}^{N_g} C_i u_i^t \right] \right\} \quad (17)$$

$$SC_i^t = \begin{cases} SC_i, & u_i^t > u_i^{t-1} \\ 0, & else \end{cases} \quad (18)$$

$$P_{g_i}^{min} \leq P_{g_i} \leq P_{g_i}^{max} \quad (19)$$

$$\sum_{i=1}^{N_g} P_{g_i}^t = load^t \quad (20)$$

Here T is the duration of study period, N_c is the number of energy carriers, N_g is the number of units, SC is the startup cost of units, C is the constant cost of units, u is the status of on or off for each units, P_g is the value of production of each units, P_g^{min} and P_g^{max} are the minimum and maximum of production of each units respectively, and $load$ is the demand in network.

The results of the implementation of FGBO and the eight mentioned algorithms are presented in Table 4. The proposed FGBO has provided the most optimal answer in this comparison at a cost of 2.1153E+07 Dollars.

The results presented in Table 4 show that the proposed FGBO algorithm is also effective in solving real-world optimization problems. FGBO has been able to provide the best quasi-optimal response than the other eight algorithms by carefully searching the search space and avoiding local optimal answers and maintaining a balance between exploration and exploitation indicators. This illustrates the obvious superiority of the FGBO over the other eight algorithms in solving the EC problem.

Table 4. Results for FGBO and other algorithms in EC problem

	Ave (Dollar)	Std (Dollar)
GA	8.5146×10^8	2.6145×10^6
PSO	5.2158×10^8	1.2485×10^6
TLBO	6.7624×10^7	5.2176×10^4
GWO	3.2648×10^7	7.5423×10^3
GOA	2.7592×10^7	8.6427×10^2
EPO	2.4257×10^7	6.5654×10^2
SGO	2.1739×10^7	2.7865×10^2
HOGO	2.2365×10^7	1.4552×10^2
FGBO	2.1153×10^7	8.6123

6. Conclusions

Heuristic optimization algorithms are increasingly being used to solve optimization problems in various applications. These algorithms can be divided into four categories: physics-based algorithm, swarm-based algorithm, game-based algorithm, and evolutionary algorithms. In this regard, a new game-based algorithm called Football game based optimization (FGBO) based on the football game is presented in this paper. FGBO is based on rules of football game which clubs and players try to achieve to victory and championship. In FGBO, football game is simulated in four phase: a) league holding, b) player transfer, c) practice, and d) promotion and relegation. With the mathematical modeling of these four phases, FGBO has been designed as an optimizer that can be used to solve optimization problems in various sciences.

The performance of FGBO is evaluated on a set of standard benchmark test functions, which is categorized to three groups named unimodal, multimodal, and fixed-dimension multimodal benchmark test functions. The results show that FGBO provides very competitive results as compared with other well-known optimization algorithms such as GA, PSO, TLBO, GWO, GOA, EPO, SGO, and HOGO.

Moreover, the proposed FGBO algorithm is used to solve the energy commitment (EC) problem. EC is a new challenge in power system studies that it can be solved with the optimization algorithms. The proposed algorithm performs well in EC problem solving than to existing algorithms.

Conflicts of Interest

The authors declare no conflict of interest.

Author Contributions

Conceptualization, M. Dehghani, M. Mardaneh, and J. M. Guerrero.; methodology, M. Dehghani and M. Mardaneh.; software, M. Dehghani and V. Kumar.; validation, J. M. Guerrero, V. Kumar, and O.P. Malik.; formal analysis, V. Kumar and O.P. Malik.; investigation, M. Dehghani and M. Mardaneh.; resources, J. M. Guerrero.; data curation, V. Kumar and O.P. Malik; writing—original draft preparation, M. Dehghani and M. Mardaneh.; writing—review and editing, V. Kumar and O.P. Malik.; visualization, M. Dehghani.; supervision, M. Dehghani.; project administration, M. Dehghani and M. Mardaneh; funding acquisition, J. M. Guerrero.

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